

Guilherme Augusto Silva Pereira

Associate Professor of Robotics – WVU

Mechanical and Aerospace Engineering Department
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Education

03/2000–11/2003 **Ph.D. in Computer Science**

Motion Planning and Control of Cooperating Mobile Robots: A Graph Connectivity Approach.

Advisors: Mario Fernando Montenegro Campos and Vijay Kumar.

Federal University of Minas Gerais (UFMG), Brazil with collaborative period at the University of Pennsylvania (UPENN), USA.

11/1998–02/2000 **M.Sc. in Electrical Engineering**

Identification and Control of Micro Mobile Robots.

Supervisor: Mario Fernando Montenegro Campos.

Federal University of Minas Gerais (UFMG), Brazil.

08/1993–10/1998 **B.Sc. in Electrical Engineering**

Senior project: Design and Development of an Autonomous Vehicle.

Supervisor: Walmir Matos Caminhas.

Federal University of Minas Gerais (UFMG), Brazil.

02/1990–12/1992 **Electronics Technician**

Federal Center for Technical Education of Minas Gerais (CEFET-MG), Brazil.

Professional Experience

10/2018–present **Associate Professor** – Department of Mechanical and Aerospace Engineering, Benjamin Statler College of Engineering and Mineral Resources, West Virginia University (WVU), USA. <http://www.wvu.edu>.

11/2018–present **Director** – Field and Aerial Robotics Laboratory (FARO), Department of Mechanical and Aerospace Engineering, Benjamin Statler College of Engineering and Mineral Resources, West Virginia University (WVU), USA.

07/2004–07/2018 **Associate Professor** – Department of Electrical Engineering, School of Engineering, Federal University of Minas Gerais (UFMG), Brazil. <http://www.ufmg.br>.

10/2004–08/2018 **Director** – Computer Systems and Robotics Laboratory (CORO), School of Engineering, Department of Electrical Engineering, Federal University of Minas Gerais (UFMG), Brazil. <http://coro.cpdee.ufmg.br>

08/2015–07/2016 **Visiting Scholar** – Field Robotics Center, Robotics Institute, Carnegie Mellon University (CMU), USA.

07/2011–07/2014 **Deputy Coordinator** – Graduate Program in Electrical Engineering (PPGEE), School of Engineering, Federal University of Minas Gerais (UFMG), Brazil. <http://www.ppgee.ufmg.br>

12/2007–05/2008 **Coordinator** – Undergraduate Program in Control and Automation Engineering, School of Engineering, Federal University of Minas Gerais (UFMG), Brazil.

05/2006–12/2007 **Deputy Coordinator** – Undergraduate Program in Control and Automation Engineering, School of Engineering, Federal University of Minas Gerais (UFMG), Brazil.

08/2003–06/2004 **Assistant Professor** – Pontifical Catholic University of Minas Gerais (PUC Minas), Brazil.

10/2001–04/2003 **Visiting Scholar** – General Robotics Automation Sensing and Perception Laboratory (GRASP Lab.), School of Engineering and Applied Science, University of Pennsylvania (UPENN), USA.

Professional Affiliations

- SENIOR MEMBER **IEEE – Institute of Electrical and Electronics Engineers.**
- Vice-chair of the Robotics and Automation Society Brazilian Chapter (2016–2017).
 - Co-founder and Chair of the Robotics and Automation Society Brazilian Chapter (2015).
 - Memberships
 - Robotics and Automation Society.
 - Intelligent Transportation Systems Society (until 2016).
- MEMBER **ASEE – American Society for Engineering Education.**
- MEMBER **SBA – Brazilian Society for Automatics.**
- Coordinator of the Robotics Technical Committee (2013–2014).

Awards/Honors

- 2016–2018 Research Productivity Fellowship, National Council for Scientific and Technological Development (CNPq), Brazil.
- 2015–2016 Postdoctoral Scholarship, National Council for Scientific and Technological Development (CNPq), Brazil.
- 2014 [The Advanced Robotics Best Paper Award](#), The Robotics Society of Japan (RSJ).
- 2013–2015 Research Productivity Fellowship, National Council for Scientific and Technological Development (CNPq), Brazil.
- 2010–2012 Research Productivity Fellowship, National Council for Scientific and Technological Development (CNPq), Brazil.
- 2009 One of four finalists for **The Student Best Paper Award** of The 2009 American Control Conference (ACC'09), The American Automatic Control Council - AACC.
- 2007–2009 Research Productivity Fellowship, National Council for Scientific and Technological Development (CNPq), Brazil.
- 2006 **The Best Poster Award** of the 12th Biennial IEEE Conference on Electromagnetic Field Computation (CEFC'06), The Institute of Electrical and Electronics Engineers - IEEE.
- 2004 One of three finalists for **The Best Conference Paper Award** of the Design Engineering Technical Conferences 2004, The American Society of Mechanical Engineers - ASME.
- 2000-2003 Doctoral Scholarship, National Council for Scientific and Technological Development (CNPq), Brazil.
- 2001-2002 Sandwich PhD Scholarship, National Council for Scientific and Technological Development (CNPq), Brazil.
- 1998-2000 Masters Scholarship, Coordination for the Improvement of Higher Education Personnel (CAPES), Brazil.
- 1998 **Gold Medal Award** for gathering the first place among the electrical engineer students in 1998, School of Engineering, Federal University of Minas Gerais, Brazil.

Citations

Google Scholar: <http://scholar.google.ca/citations?user=gd8q19oAAAAJ>
ResearcherID: <http://www.researcherid.com/rid/E-5773-2010>

GOOGLE SCHOLAR Papers: **125** Citations: **2474** H-index: **23** Date: Dec 16, 2020
WEB OF SCIENCE Papers: **70** Citations: **942** H-index: **17** Date: Dec 16, 2020
SCOPUS Papers: **63** Citations: **1214** H-index: **18** Date: Aug 27, 2020

Peer-reviewed journal papers (30)

1. R. M. Gago, M. Y. A. Pereira, and **G. A. S. Pereira**, “An Aerial Robotic System for Inventory of Stockpile Warehouses,” *Engineering Reports*, pp. e12396, 2021. DOI: [10.1002/eng2.12396](https://doi.org/10.1002/eng2.12396)
2. D. Shapovalov and **G. A. S. Pereira**, “Tangle-Free Exploration with a Tethered Mobile Robot,” *Remote Sensing*, vol 12, issue 23, pp. 3858, 2020. DOI: [10.3390/rs12233858](https://doi.org/10.3390/rs12233858) *JCR Impact Factor 2019*: 4.509
3. **G. A. S. Pereira** and E. J. R. Freitas, “Navigation of Semi-autonomous Service Robots using Local Information and Anytime Motion Planners,” *Robotica*, vol 38, issue 11, pp. 2080–2098, November 2020. DOI: [10.1017/S0263574719001838](https://doi.org/10.1017/S0263574719001838) *JCR Impact Factor 2019*: 1.509
4. V. M. Gonçalves, R. McLaughlin, and **G. A. S. Pereira**, “Precise Landing of Autonomous Aerial Vehicles using Vector Fields,” *IEEE Robotics and Automation Letters*, vol 5, issue 3, pp. 4337–4344, July 2020. DOI: [10.1109/LRA.2020.2994485](https://doi.org/10.1109/LRA.2020.2994485) *JCR Impact Factor 2019*: 3.608
5. A. C. B. Chiella, H. N. Machado, B. O. Teixeira, and **G. A. S. Pereira**, “GNSS/LiDAR-Based Navigation of an Aerial Robot in Sparse Forests,” *Sensors*, vol 19, issue 19, pp. 4061, 2019. DOI: [10.3390/s19194061](https://doi.org/10.3390/s19194061) *JCR Impact Factor 2019*: 3.275
6. A. C. B. Chiella, B. O. Teixeira, and **G. A. S. Pereira**, “Quaternion-Based Robust Attitude Estimation Using an Adaptive Unscented Kalman Filter,” *Sensors*, vol 19, issue 10, pp. 2372, 2019. DOI: [10.3390/s19102372](https://doi.org/10.3390/s19102372) *JCR Impact Factor 2019*: 3.275
7. R. F. Santos, **G. A. S. Pereira**, and L. A. Aguirre, “Learning Robot Reaching Motions by Demonstration using Nonlinear Autoregressive Models,” *Robotics and Autonomous Systems*, vol 107, pp. 182–195, September 2018. DOI: [10.1016/j.robot.2018.06.006](https://doi.org/10.1016/j.robot.2018.06.006) *JCR Impact Factor 2019*: 2.825
8. R. J. Alitappeh, **G. A. S. Pereira**, A. R. Araújo, and L. C. A. Pimenta, “Multi-robot Deployment using Topological Maps,” *Journal of Intelligent & Robotic Systems*, vol 86, issue 3, pp. 641–661, June 2017. DOI: [10.1007/s10846-017-0471-3](https://doi.org/10.1007/s10846-017-0471-3) *JCR Impact Factor 2019*: 2.259
9. G. S. C. Avellar, **G. A. S. Pereira**, L. C. A. Pimenta, and P. Iscold, “Multi-UAV Routing for Area Coverage and Remote Sensing with Minimum Time,” *Sensors*, vol 15, pp. 27783–27803, 2015. DOI: [10.3390/s151127783](https://doi.org/10.3390/s151127783) *JCR Impact Factor 2019*: 3.275
10. N. C. Batista and **G. A. S. Pereira**, “A Probabilistic Approach for Fusing People Detectors,” *Journal of Control, Automation and Electrical Systems*, vol 26, pp. 616–629, 2015. DOI: [10.1007/s40313-015-0202-6](https://doi.org/10.1007/s40313-015-0202-6)
11. J. E. A. Dias, **G. A. S. Pereira**, and R. M. Palhares, “Longitudinal Model Identification and Velocity Control of an Autonomous Car,” *IEEE Transactions on Intelligent Transportation Systems*, vol. 16, no. 2 pp. 776–786, April 2015. DOI: [10.1109/TITS.2014.2341491](https://doi.org/10.1109/TITS.2014.2341491) *JCR Impact Factor 2019*: 6.319
12. D. N. Brito, F. L. C. Pádua, and **G. A. S. Pereira**, “Temporal Synchronization in Mobile Sensor Networks Using Image Sequence Analysis,” *Machine Vision and Applications*, vol. 25, no. 4, pp. 1067–1076, May 2014. DOI: [10.1007/s00138-014-0605-6](https://doi.org/10.1007/s00138-014-0605-6) *JCR Impact Factor 2019*: 1.605
13. L. C. A. Pimenta, **G. A. S. Pereira**, M. M. Gonçalves, N. Michael, M. Turpin, and V. Kumar, “Decentralized Controllers for Perimeter Surveillance with Teams of Aerial Robots,” *Advanced Robotics*, vol. 27, pp. 697–709, 2013. (This paper won **The Advanced Robotics Best Paper Award 2014**.) DOI: [10.1080/01691864.2013.778942](https://doi.org/10.1080/01691864.2013.778942) *JCR Impact Factor 2019*: 1.247
14. L. C. A. Pimenta, **G. A. S. Pereira**, N. Michael, R. C. Mesquita, M. M. Bosque, L. Chaimowicz, and V. Kumar, “Swarm Coordination Based on Smoothed Particle Hydrodynamics Technique,” *IEEE Transactions on Robotics*, vol. 29, no. 2, pp. 383–399, April 2013. DOI: [10.1109/TRO.2012.2234294](https://doi.org/10.1109/TRO.2012.2234294) *JCR Impact Factor 2019*: 6.123
15. D. A. Lima and **G. A. S. Pereira**, “Navigation of an Autonomous Car using Vector Fields and the Dynamic Window Approach,” *Journal of Control, Automation and Electrical Systems*, vol. 24, no. 1-2, pp. 106–116, April 2013. DOI: [10.1007/s40313-013-0006-5](https://doi.org/10.1007/s40313-013-0006-5)
16. D. N. Brito, F. L. C. Pádua, **G. A. S. Pereira**, and R. L. Carceroni, “Temporal Synchronization of Non-overlapping Videos using Known Object Motion,” *Pattern Recognition Letters*, vol. 32, no. 1, pp. 38–46, January 2011. DOI: [10.1016/j.patrec.2010.02.011](https://doi.org/10.1016/j.patrec.2010.02.011) *JCR Impact Factor 2019*: 3.255

17. M. A. G. Moreira, **G. A. S. Pereira**, L. A. B. Torres, and P. Iscold, "Localization, Modelling, and Control of a Mini-helicopter in Indoor Environments," *Controle & Automação*, vol. 22, no. 3, pp. 238–255, May/June 2011. DOI: [10.1590/S0103-17592011000300003](https://doi.org/10.1590/S0103-17592011000300003)
18. P. Iscold, **G. A. S. Pereira**, and L. A. B. Torres, "The Development of a Hand-launched Small UAV for Ground Reconnaissance," *IEEE Transactions on Aerospace and Electronic Systems*, vol. 46, no. 1, pp. 335–348, January 2010. DOI: [10.1109/TAES.2010.5417166](https://doi.org/10.1109/TAES.2010.5417166) *JCR Impact Factor 2019*: 3.672
19. V. M. Gonçalves, L. C. A. Pimenta, C. A. Maia, B. C. O. Dutra, and **G. A. S. Pereira**, "Vector Fields for Robot Navigation Along Time-varying Curves in n -dimensions," *IEEE Transactions on Robotics*, vol. 26, no. 4, pp. 647–659, August 2010. DOI: [10.1109/TRO.2010.2053077](https://doi.org/10.1109/TRO.2010.2053077) *JCR Impact Factor 2019*: 6.123
20. V. M. Gonçalves, L. C. A. Pimenta, C. A. Maia, and **G. A. S. Pereira**, "Robot Navigation using Implicit Curves," *Controle & Automação*, vol. 21, no. 1, pp. 43–57, January/February 2010. DOI: [10.1590/S0103-17592010000100004](https://doi.org/10.1590/S0103-17592010000100004)
21. **G. A. S. Pereira**, L. C. A. Pimenta, L. Chaimowicz, A. R. Fonseca, D. S. C. Almeida, L. Q. Corrêa, R. C. Mesquita, and M. F. M. Campos, "Robot Navigation in Multi-terrain Outdoor Environments," *The International Journal of Robotics Research*, vol. 28, no. 6, pp. 685–700, June 2009. DOI: [10.1177/0278364908097578](https://doi.org/10.1177/0278364908097578) *JCR Impact Factor 2019*: 4.706
22. **G. A. S. Pereira**, V. Kumar, and M. F. M. Campos, "Closed Loop Motion Planning of Cooperating Mobile Robots using Graph Connectivity," *Robotics and Autonomous Systems*, vol. 56, no. 4, pp. 373–384, April 2008. DOI: [10.1016/j.robot.2007.08.003](https://doi.org/10.1016/j.robot.2007.08.003) *JCR Impact Factor 2019*: 2.825
23. **G. A. S. Pereira**, P. Iscold, and L. A. B. Torres, "Airplane Attitude Estimation using Computer Vision: Simple Method and Actual Experiments," *Electronics Letters*, vol. 44, no. 22, pp. 1303–1305, October 2008. DOI: [10.1049/el:20081184](https://doi.org/10.1049/el:20081184) *JCR Impact Factor 2019*: 1.316
24. D. A. P. Nagem, M. A. G. Moreira, **G. A. S. Pereira**, C. J. Tierra-Criollo, M. B. Pinotti, "Development of the Relations for the Interphalange and Metacharpo-phalange During Grasp Movement," *Matéria*, vol. 12, pp. 179–185, 2007. DOI: [10.1590/S1517-70762007000100023](https://doi.org/10.1590/S1517-70762007000100023)
25. L. C. A. Pimenta, M. L. Mendes, R. C. Mesquita, and **G. A. S. Pereira**, "Fluids in Electrostatic Fields: An analogy for Multi-robot Control," *IEEE Transactions on Magnetics*, vol. 43, no. 4, pp. 1765–1768, April 2007. DOI: [10.1109/TMAG.2007.892514](https://doi.org/10.1109/TMAG.2007.892514) *JCR Impact Factor 2019*: 1.626
26. **G. A. S. Pereira**, M. F. M. Campos, and L. A. Aguirre, "Data-based Dynamical Modeling of Externally Observed Actuators-only Robots," *IEEE Transactions on System, Man, and Cybernetics - Part A*, vol. 36, no. 4, pp. 706–717, July 2006. DOI: [10.1109/tsmca.2005.854372](https://doi.org/10.1109/tsmca.2005.854372)
27. L. C. A. Pimenta, A. R. Fonseca, **G. A. S. Pereira**, R. C. Mesquita, E. J. Silva, W. M. Caminhas, and M. F. M. Campos, "Robot Navigation based on Electrostatic Field Computation," *IEEE Transactions on Magnetics*, vol. 42, no. 4, pp. 1459–1462, April 2006. DOI: [10.1109/TMAG.2006.870931](https://doi.org/10.1109/TMAG.2006.870931) *JCR Impact Factor 2019*: 1.626
28. F. Zhang, **G. A. S. Pereira**, and V. Kumar, "Cooperative Localization and Tracking in Distributed Robot-Sensor Networks," *Tsinghua Science and Technology*, vol. 10, no. 1, pp. 91–101, Feb. 2005. DOI: [10.1016/S1007-0214\(05\)70014-6](https://doi.org/10.1016/S1007-0214(05)70014-6)
29. **G. A. S. Pereira**, V. Kumar, and M. F. M. Campos, "Decentralized Algorithms for Multi-Robot Manipulation via Caging," *The International Journal of Robotics Research*, vol. 23, no. 7, pp. 783–795, July 2004. DOI: [10.1177/0278364904045477](https://doi.org/10.1177/0278364904045477) *JCR Impact Factor 2019*: 4.706
30. M. F. M. Campos, **G. A. S. Pereira**, S. R. C. Vale, A. Q. Bracarense, G. A. Pinheiro, and M. P. Oliveira, "A Robot for Installation and Removal of Aircraft Warning Spheres on Aerial Power Transmission Lines," *IEEE Transactions on Power Delivery*, vol. 18, no. 4, pp. 1581–1582, October 2003. DOI: [10.1109/TPWRD.2003.817538](https://doi.org/10.1109/TPWRD.2003.817538) *JCR Impact Factor 2019*: 3.681

Book chapters (12)

1. E. J. R. Freitas and **G. A. S. Pereira**, "Uma Estratégia para Navegação de Robôs de Serviço Semiautônomos usando informação local e planejadores probabilísticos," in *Tecnologias, Métodos e Teorias na Engenharia de Computação*, E. R. Martins Ed. Ponta Grossa, PR: Atena, 2020, pp. 196–213. [10.22533/at.ed.613200409](https://doi.org/10.22533/at.ed.613200409)
2. L. Chaimowicz, **G. A. S. Pereira**, and M. F. M. Campos, "Robótica Cooperativa," in *Robótica Móvel*, R. A. F. Romero, E. Prestes, F. Osório, and D. F. Wolf. Eds. Rio de Janeiro: LTC - Livros Técnicos e Científicos Editora Ltda., 2014, vol. 1, pp. 242–255.

3. L. C. A. Pimenta, M. Schwager, Q. Lindsey, V. Kumar, D. Rus, R. C. Mesquita, and **G. A. S. Pereira**, “Simultaneous coverage and tracking (SCAT) of moving target with robot networks,” in *Algorithmic Foundations of Robotics VIII - Selected Contributions of the Eighth International Workshop on the Algorithmic Foundations of Robotics*, 1st ed., G. S. Chirikjian, H. Choset, M. Morales, and T. Murphey, Eds. Springer-Verlag, 2010, vol. 57, pp. 85–99. DOI: [10.1007/978-3-642-00312-7_6](https://doi.org/10.1007/978-3-642-00312-7_6)
4. **G. A. S. Pereira**, L. C. A. Pimenta, L. Chaimowicz, A. R. Fonseca, D. S. C. de Almeida, L. de Q. Corrêa, R. C. Mesquita, and M. F. M. Campos, “Robot navigation in multi-terrain outdoor environments,” in *Experimental Robotics: The 10th International Symposium on Experimental Robotics*, ser. STAR - Springer Tracts on Advanced Robotics, O. Khatib, V. Kumar, and D. Rus, Eds. Springer-Verlag, 2008, vol. 39, pp. 331–342. [10.1007/978-3-540-77457-0_31](https://doi.org/10.1007/978-3-540-77457-0_31)
5. **G. A. S. Pereira** and L. Chaimowicz, “Robôs móveis,” in *Enciclopédia de Automática: Controle e Automação*, L. A. Aguirre, A. P. A. da Silva, M. F. M. Campos, and W. C. do Amaral, Eds. São Paulo: Editora Blucher, 2007, vol. 3, pp. 369–386.
6. A. R. Fonseca, L. C. A. Pimenta, R. C. Mesquita, R. R. Saldanha, and **G. A. S. Pereira**, “Path planning for mobile robots operating in outdoor environments using map overlay and triangular decomposition,” in *ABCm Symposium Series in Mechatronics*. Ouro Preto, Brasil: Associação Brasileira de Engenharia e Ciências Mecânicas, Novembro 2006, vol. 2, pp. 218–225.
7. G. Kantor, S. Singh, R. Peterson, D. Rus, A. K. Das, V. Kumar, **G. A. S. Pereira**, and J. Spletzer, “Distributed search and rescue with robot and sensor teams,” in *Field and Service Robotics: Recent Advances in Research and Applications*, ser. STAR - Springer Tracts on Advanced Robotics, H. Asama, S. Yuta, S. Thrun, and E. Prassler, Eds. Springer-Verlag, 2006, vol. 24, pp. 529–538. DOI: [10.1007/10991459_51](https://doi.org/10.1007/10991459_51)
8. C. Belta, **G. A. S. Pereira**, and V. Kumar, “Abstraction and control for swarms of robots,” in *Robotics Research*, ser. STAR, P. Dario and R. Chatila, Eds. Springer-Verlag, 2005, pp. 224–233. DOI: [10.1007/11008941_24](https://doi.org/10.1007/11008941_24)
9. **G. A. S. Pereira**, V. Kumar, and M. F. M. Campos, “Decentralized algorithms for multirobot manipulation via caging,” in *Algorithmic Foundations of Robotics V*, ser. STAR, J. D. Boissonnat, J. Burdick, K. Goldberg, and S. Hutchinson, Eds. Heidelberg: Springer-Verlag, 2004, pp. 257–273. DOI: [10.1007/978-3-540-45058-0_16](https://doi.org/10.1007/978-3-540-45058-0_16)
10. **G. A. S. Pereira**, A. Das, V. Kumar, and M. F. M. Campos, “Decentralized motion planning for multiple robots subject to sensing and communication constraints,” in *Multi-Robot Systems: From Swarms to Intelligent Automata, Volume II*, A. Schultz, L. E. Parker, and F. Schneider, Eds. Kluwer Academic Press, 2003, pp. 267–278.
11. **G. A. S. Pereira**, V. Kumar, J. Spletzer, C. J. Taylor, and M. F. M. Campos, “Cooperative transport of planar objects by multiple mobile robots using object closure,” in *Experimental Robotics VIII*, ser. STAR, B. Siciliano and P. Dario, Eds. Heidelberg: Springer-Verlag, 2003, pp. 275–284. DOI: [10.1007/3-540-36268-1_25](https://doi.org/10.1007/3-540-36268-1_25)
12. M. F. M. Campos, A. Q. Bracarense, **G. A. S. Pereira**, G. A. Pinheiro, M. P. Oliveira, and S. R. C. Vale, “Robotized installation of signaling aerial spheres in transmission lines cables,” in *Intelligent Assembly and Disassembly 2001*, P. Kopacek, C. E. Pereira, and D. Noe, Eds. Elsevier Science Ltd, 2002, pp. 91–100.

Peer-reviewed papers in international conferences (30)

1. B. Martinez R. Junior and **G. A. S. Pereira**, “Fast Path Computation using Lattices in the Sensor-Space for Forest Navigation”, in *Proceedings of the IEEE International Conference on Robotics and Automation (ICRA’21)*, Xi’an, China, May 2020 (Acceptance rate: 48%).
2. D. Shapovalov and **G. A. S. Pereira**, “Exploration of unknown environments with a tethered mobile robot”, in *Proceedings of the IEEE/RSJ International Conference on Intelligent Robot and Systems (IROS’20)*, Las Vegas, October 2020, pp. 6826–6831. (Acceptance rate: 47%). DOI: [10.1109/IROS45743.2020.9340993](https://doi.org/10.1109/IROS45743.2020.9340993)
3. N. Dhanaraj, N. Hewitt, C. Edmonds-Estes, R. Jarman, J. Seo, H. Gunner, A. Hatfield, T. Johnson, L. Yifru, J. Maffeo, **G. Pereira**, J. Gross, and Y. Gu, “Adaptable Platform for Interactive Swarm Robotics (APIS): A Human-Swarm Interaction Research Testbed”, *Proceedings of the International Conference on Advanced Robotics (ICAR’19)*, Belo Horizonte, December 2019, pp. 720–726. (Acceptance rate: 56%). DOI: [10.1109/ICAR46387.2019.8981628](https://doi.org/10.1109/ICAR46387.2019.8981628)
4. A. C. B. Chiella, B. O. Teixeira, and **G. A. S. Pereira**, “State Estimation for Aerial Vehicles in Forest Environments”, in *Proceedings of the International Conference on Unmanned Aircraft Systems (ICUAS’19)*, Atlanta, June 2019, pp. 882–890. DOI: [10.1109/ICUAS.2019.8797822](https://doi.org/10.1109/ICUAS.2019.8797822)
5. A. C. B. Chiella, B. O. Teixeira, and **G. A. S. Pereira**, “Robust Attitude Estimation Using an Adaptive Unscented Kalman Filter”, in *Proceedings of the IEEE International Conference on Robotics and Automation (ICRA’19)*, Montreal, May 2019, pp. 7748–7754 (Acceptance rate: 44%). DOI: [10.1109/ICRA.2019.8793714](https://doi.org/10.1109/ICRA.2019.8793714)

6. **G. A. S. Pereira**, S. Choudhury, and S. Scherer, “A framework for optimal repairing of vector field-based motion plans,” in *Proceedings of the International Conference on Unmanned Aircraft Systems (ICUAS’16)*, Arlington, June 2016, pp. 405–846. DOI: [10.1109/ICUAS.2016.7502525](https://doi.org/10.1109/ICUAS.2016.7502525)
7. A. R. Araújo, D. D. Caminhas, and **G. A. S. Pereira**, “An architecture for navigation of service robots in human-populated office-like environments,” In *Proceedings of the 11th IFAC Symposium on Robot Control (SYROCO’15)*, Salvador, August 2015, p. 1–6. DOI: [10.1016/j.ifacol.2015.12.032](https://doi.org/10.1016/j.ifacol.2015.12.032)
8. V. M. Gonçalves, L. C. A. Pimenta, C. A. Maia, and **G. A. S. Pereira**, “Coordination of multiple fixed-wing UAVs traversing intersecting periodic paths,” in *Proceedings of the IEEE International Conference on Robotics and Automation (ICRA’13)*, Karlsruhe, May 2013, pp. 841–846. (Acceptance rate: 39%) DOI: [10.1109/ICRA.2013.6630672](https://doi.org/10.1109/ICRA.2013.6630672)
9. G. S. C. Avellar, G. D. Thums, R. R. Lima, P. Iscold, L. A. B. Torres, and **G. A. S. Pereira**, “On the development of a small hand-held multi-UAV platform for surveillance and monitoring,” in *Proceedings of the International Conference on Unmanned Aircraft Systems (ICUAS’13)*, Atlanta, May 2013, pp. 405–846. DOI: [10.1109/ICUAS.2013.6564715](https://doi.org/10.1109/ICUAS.2013.6564715)
10. M. M. Gonçalves, L. C. A. Pimenta, and **G. A. S. Pereira**, “Coverage of curves in 3D with swarms of nonholonomic aerial robots,” in *Proceedings of the IFAC World Congress*, vol. 18, 2011, pp. 10367–10372. DOI: [10.3182/20110828-6-IT-1002.03723](https://doi.org/10.3182/20110828-6-IT-1002.03723)
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Press Coverage

- Drone Activity on WVU's Summer Camp – [Dominion Post](#) (News Paper) – 2019
- Interview on Drone Delivery – ComCiência Magazine – 2019
- Interview on Autonomous Safety Systems – Correio Braziliense (News Paper) – 2016.
- Interview on Jobs and Robots – Zero Hora de Porto Alegre (News Paper) – 2015.
- Interview on Robotics – Portal Terra (On-line News Paper) – 2013.
- Autonomous Car developed at UFMG (CADU) covered by several TV networks and news papers in Brazil (TV GLOBO, SBT, TV UFMG, Jornal do Brasil, Hoje em Dia, Estado de Minas, O Tempo, Revista Encontro, Pesquisa Fapesp, Revista FAPEMIG, Radio Itatiaia) – [2009-2015]. Some videos here: <https://goo.gl/zEJkhH>

Editorial Boards

- 10/2020–present **IEEE Robotics and Automation Letters**, IEEE – Associate Editor.
- 01/2020–present **Journal of Intelligent & Robotic Systems**, Springer – Lead Guest Editor.
- 01/2016–present **Learning & Nonlinear Models** – Associate Editor.
- 01/2013–12/2018 **Journal of Control, Automation and Electrical Systems**, Springer – Associate Editor.
- 01/2010–12/2012 **Revista Controle & Automação** – Associate Editor.

Organization of Scientific Events

- International Conference on Advanced Robotics (ICAR), Belo Horizonte, MG, Brazil, December 2019 – Program Chair.
- Congresso Brasileiro de Automática (CBA), Belo Horizonte, MG, Brazil, September 2014 – Technical Committee.
- International Symposium on Experimental Robotics (ISER), Rio de Janeiro, RJ, Brazil, June 2006 – Local Committee.

Program Committees of Scientific Events

- Congresso Brasileiro de Automática (CBA), 2018.
- IEEE Latin American Robotics Symposium (LARS), 2018.
- IEEE Latin American Robotics Symposium (LARS), 2017.
- IEEE Intelligent Transportation Systems Conference (ITSC), 2017.
- Simpósio Brasileiro de Automação Inteligente (SBAI), 2017.
- IEEE Intelligent Transportation Systems Conference (ITSC), 2016.
- IEEE Latin American Robotics Symposium (LARS), 2016
- IEEE/IFIP International Workshop on Urban Mobility and Intelligent Transportation Systems (UMITS), 2016.
- Simpósio Brasileiro de Automação Inteligente (SBAI), 2015.
- IFAC Symposium on Robot Control (SYROCO), 2015.
- IEEE International Symposium on Industrial Electronics (ISIE) – Robotics & Mechatronics Track, 2015
- Simpósio Brasileiro de Automação Inteligente (SBAI), 2013.
- Congresso Brasileiro de Robótica (CBR), 2012.
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- VII Seminário Internacional de Metrologia Elétrica (SEMETRO), 2007.
- Encontro de Robótica Inteligente (ENRI), 2006.

Reviews

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- **JOURNALS:** Journal of Field Robotics, IEEE Transactions on Robotics, IEEE Robotics and Automation Letters, Journal of Intelligent & Robotic Systems, Sensors, IEEE Transactions on Control of Network Systems, IEEE Sensors Journal, IEEE Transactions on Automation Science and Engineering, IEEE Transactions on Robotics and Automation, Robotica, Automática, IEEE Intelligent Systems, Robotics and Autonomous Systems, Robotica, Intelligent Service Robotics, IEEE Transactions on Instrumentation and Measurement, Pattern Analysis and Applications, Journal of the Brazilian Society of Mechanical Sciences and Engineering, Journal of Control, Automation and Electrical Systems, Revista Controle & Automação.
- **CONFERENCES:** IEEE International Conference on Robotics and Automation (ICRA), IEEE/RJS International Conference on Intelligent Robots and Systems (IROS), American Control Conference (ACC), International Conference on Unmanned Aircraft Systems (ICUAS), IEEE International Conference on Decision and Control (CDC), IEEE Intelligent Vehicles Symposium (IV), IEEE Intelligent Transportation Systems Conference (ITSC), AIAA Guidance Navigation and Control Conference, International Symposium on Distributed Autonomous Robotic Systems (DARS), IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM), Congresso Brasileiro de Automática (CBA), Simpósio Brasileiro de Automação Inteligente (SBAI), Simpósio Brasileiro de Robótica (SBR).
- **FUNDING AGENCIES:** National Council for Scientific and Technological Development (CNPq/Brazil), Coordination for the Improvement of Higher Education Personnel (CAPES/Brazil).

Committees

- **PHD COMMITTEES:** West Virginia University (2 committees), Federal University of Minas Gerais (18 committees), University of São Paulo (4), Federal University of Rio de Janeiro (2), Federal University of Itajubá (1), Federal University of Campina Grande (1), Federal University of Rio Grande do Norte (1), Federal University of Juiz de Fora (1), University of Campinas (1), Federal University of Uberlândia (1).
- **QUALIFY AND MASTERS COMMITTEES:** West Virginia University (3q+3m committees), Federal University of Minas Gerais (26q+40m), University of São Paulo (6q+1m), Federal University of Rio de Janeiro (1q+1m), Federal University of Campina Grande (1q), Federal University of Rio Grande do Norte (1q), Pontifical Catholic University of Minas Gerais (2m), Federal Center for Technological Education of Minas Gerais (2m), University of Brasília (1m), Federal University of Juiz de Fora (1m).
- **SENIOR PROJECT COMMITTEES:** 39 committees at the Federal University of Minas Gerais.
- **FACULTY SEARCH COMMITTEES:** 3 committees at West Virginia University; 11 committees at the Federal University of Minas Gerais.
- **POSTDOC SEARCH COMMITTEES:** 2 committees at West Virginia University.

Invited Presentations and Lectures

- Universidade de São Paulo (USP), São Carlos, MG, Brazil – May 2019.
- CORA Robotics Competition, Belo Horizonte, MG, Brazil – August 2017.
- IEEE Student Branch (UFMG), Belo Horizonte, MG, Brazil – October 2016.
- Brazilian Society for Automotive Engineering (AEA), São Paulo, SP, Brazil – May 2014.
- Universidade Federal do Amazonas (UFAM), Manaus, AM, Brazil – January 2014.
- Instituto Federal de Ciência e Tecnologia do Amazonas (IFAM), Manaus, AM, Brazil – May 2011.
- Universidade Federal de Juiz de Fora (UFJF), Juiz de Fora, MG, Brazil – June 2011.
- GRASP Laboratory, University of Pennsylvania (UPENN), Philadelphia, PA, USA – June 2009.

Educational Projects

- 2013-2018 **BRAFITEC – Computer Science and Engineering education in Brazil and France in the perspective of biosystems.**
Objective: Exchange of undergraduate students between UFMG/Brazil and the University of Technology of Compiègne (UTC/France).
Role: Local Project Coordinator.
Funding: Coordination for the Improvement of the Higher Level Personnel (CAPES).
- 2005-2007 **RICEE – Robotics as the integration of knowledge in Electrical Engineering and Control and Automation Engineering .**
Objective: Equipping teaching laboratories.
Role: Project Coordinator
Funding: ATAN Sistemas.

Student Advising

PH.D. STUDENTS (6)

1. Rogério Rodrigues Lima - expected graduation date: 2024.
2. Bernardo Martinez Rocamora Junior - expected graduation date: 2024.
3. Antônio Carlos Bana Chiella - State estimation of aerial vehicles flying near the ground, 2019.
4. Rafael Francisco do Santos - Robot programming by demonstration using system identification, 2018.
5. Natália Cosse Batista - A Probabilistic Approach for Fusing People Detectors, 2015.
6. Luciano Cunha de Araújo Pimenta (co-supervision) - Techniques for controlling swarms of robots, 2009.

M.SC. STUDENTS (20)

1. Al Mahmud - Development of collision resilient drone, expected graduation date: 2021.
2. Danylo Shapovalov - Exploration of Unknown Environments Using a Tethered Mobile Robot, 2020.
3. Henrique Nunes Machado - Planning based obstacle avoidance for aerial vehicles, 2020.
4. Elias José de Rezende Freitas - Navigation of service robots using vector fields sampling based planners, 2017.
5. Diana Sabina Albán Penafiel - A home-helping robot, 2014.
6. Gustavo Silva Castilho de Avellar - Area coverage with groups of aerial robots in minimal time, 2014.
7. Alexandre Moares Tannus (co-supervision) - Control of a robotic wheelchair using electroencephalographic signals, 2014.
8. Gabriel Silva Ribeiro (co-supervision) - Hardware-in-the-loop simulation of Inertial Measurement Units, 2014.
9. Jullierme Emiliano Alves Dias - Longitudinal control of an autonomous car, 2013.
10. Tiago Amadeu Arruda - Hardware and software architecture for an autonomous car, 2012.
11. Mateus Mariano Gonçalves - Navigation of aerial robots swarms, 2011.
12. João Bosco Silvino Júnior - Computer vision for Forensic Ballistics, 2010.
13. Marco Aurélio Guimarães Moreira - Identification and control of an autonomous helicopter, 2010.
14. Danilo Alves de Lima - Autonomous cars navigation using vector fields and the dynamic window approach, 2010.
15. Michelle Mendes Santos (co-supervision) - Sensor fusion for localization of an autonomous car, 2009.
16. Turbío Tanus Salis - Computer vision on the siderurgic industry, 2008.
17. Raoni Maira Resende - Human/robot interface using computer vision and discrete event systems, 2006.

18. Alexandre Ramos Fonseca (co-supervision) - Map composition for robot navigation, 2006.
19. Luciano Cunha de Araújo Pimenta - Robot navigation based on Laplace's Equation, 2005.
20. Marcelo Borghetti Soares (co-supervision) - Data extraction on wireless sensor networks using mobile robots, 2004.

UNDERGRADUATE STUDENTS

- Research Apprenticeship Program (RAP): 4 students at WVU.
- Scientific Initiation students and laboratory interns: 3 students at WVU, 49 students at UFMG
- Senior projects in Control and Automation Engineering and Electrical Engineering: 35 students at UFMG.

Courses taught

GRADUATE LEVEL

Robot Motion Planning,
 Probabilistic Robotics,
 Robot Kinematics I,
 Robot Navigation,
 Robot Navigation II - Advanced Motion Planning,
 Robot Motion Planning and Control,
 Image Detection and Analysis,
 Data Structures and Algorithms.

UNDERGRADUATE LEVEL

Mechatronics, *videos of final projects 2019*: shorturl.at/fnqDH,
 Robotic Manipulators, *videos of final projects*:
 UFMG: goo.gl/G7m5x3,
 WVU 2019: youtu.be/ycTx04xaLoM,
 WVU 2020: shorturl.at/kCMPS,

Introduction to Robotics,
 Control of Electrical Drives Laboratory,
 Electrical Machines Laboratory,
 Electric Circuits,
 Electric Circuits Laboratory,
 Control Systems,
 Digital Systems Laboratory,
 Logics.

EXTENSION AND OUTREACH

Image Detection and Analysis (extension course – eight weeks),
 A Ludic Introduction to Robotics (outreach in summer festival – four days),
 Introduction to Aerial Robotics (conference tutorial – three days),
 A Ludic Introduction to Drone Programming (outreach in summer camp – three hours)

Research experience

- Field and Service Robotics (mobile robots, autonomous cars, unmanned aircrafts)
- Robot Motion Planning (deterministic and stochastic planners, vector fields, optimal planners)
- Aerial robotics (fixed-wing, rotorcrafts, guidance, landing, state estimation)
- Cooperative Robotics (localization, manipulation, coordination, planning and control)
- Computer Vision (stereo vision, localization, visual servoing)
- Sensor Fusion (localization, path reconstruction, people detection)
- System Identification (modeling dynamic system for prediction and control, programming by demonstration)

Development experience

Videos can be found at: <https://goo.gl/213Ew4>

AUTONOMOUS VEHICLES AND ROBOTS DEVELOPED (in collaboration with students and colleagues)

- Robotic wheelchair - Principal Investigator - 2014–2017
- Service Robot (MARIA) - Principal Investigator - 2014–2017
- Team of fixed-wings aerial vehicles - Researcher - 2010–2014
- UFMG's Autonomous Car (CADU) - Principal Investigator - 2007–2014
- Autonomous Helimodel - Principal Investigator - 2009–2010
- Team of 4 cooperative holonomic mobile robots - part of PhD work - 2002
- Lego based mobile manipulators (Manuelzão and Miguelin) - part of PhD work - 2001
- Mobile robot for installation of warning spheres in power transmission lines - Developer of electronics and control - 2000–2001
- Indoors autonomous vehicle (SUCATA) - Engineering Senior Project - 1998
- Team of 3 robotic soccer players (Teams UAI and MIneiROSOT) - non-curricular undergraduate activities - 1997–1998

SOFTWARE DEVELOPMENT EXPERIENCE

- Languages: C, C++, Matlab, Python, Pascal.
- Libraries and tools: Robot Operating System (ROS), The Open Motion Planning Library (OMPL), Open Source Computer Vision (OpenCV), Visual Servoing Platform (ViSP), Stage, Gazebo, Robotics Matlab Toolbox.
- Operating systems: Linux, MS Windows.
- [ROS packages maintained](#): 2

EXPERIENCE WITH COMMERCIAL ROBOTS AND SENSORS

- Aerial robotics: DJI Matrice 100 quadrotor, Intel Aero RTF quadrotor, Ryse Tello Edu, Micropilot MP2028.
- Ground mobile robots: Adept Pionner 3-AT, iRobot Create I and II, Nomad 200 and 500.
- Manipulator robot: Universal Robots UR3, Comau Smart 6.
- Educational robotics: Arduino, Lego (EV3, NXT and RCX), MIT Handy Board.
- Laser range finders: Sick (LMS-100, LMS-200), Hokuyo (UTM-30LX, URG-04LX), Lightware SF30.
- Cameras: Point Grey (Bumblebee, Dragonfly and Firefly), MS Kinect, USB Cameras. Analog Frame Grabbers.

PARTICIPATION IN ROBOTICS COMPETITIONS

- NASA Space Robotics Challenge 2, virtual/simulated competition, 2020.
- MBZIRC - Abu Dhabi, 2017 (Mohamed Bin Zayed International Robotics Challenge) - Participated with the Carnegie Mellon Tartans Team in Challenge 1 (Landing on a Moving Platform).
- Robocup Brazil - Fortaleza, 2013 - Second place in Robocup@home category.
- Robot Soccer Brazilian Cup - São Paulo, 1998; Porto Alegre, 1999 - First place in 1999.
- Robocup/FIRA - Paris, 1998 - Participation in the very small size robot soccer category.

Funded Research Projects

CURRENT PROJECTS

- 2020-2021 **Development of an Intelligent Farming Robot.**
Role: Principal Investigator
Funding: West Virginia University – US\$11,000.00
- 2020-2021 **Parallel and cloud computing for long-term robotics.**
Role: Principal Investigator
Funding: Amazon Research Awards (ARA) – US\$84,000.00
- 2019-2022 **Autonomous Robotic Early Warning System for Underground Stone Mining Safety.**
Role: Co-Principal Investigator
Funding: Alpha Foundation for the Improvement of Mine Safety and Health – US\$748,968.00

PREVIOUS PROJECTS (Average Dollar quotation since 2005: US\$1.00 \approx R\$2.50; current quotation: US\$1.00 \approx R\$4.10 – Obs: most Brazilian projects do not include salaries.)

- 2019-2020 **Tethered Drones for Long-Term Exploration Missions.**
Role: Principal Investigator
Funding: NASA WV EPSCoR – US\$22,231.00
- 2016-2022 **National Institute of Science and Technology for Cooperative Autonomous Systems Applied to Security and Environment.**
Role: Co-Principal Investigator until 10/2018
Funding: National Council for Scientific and Technological Development (CNPq/Brazil) – R\$7,100,000.00
- 2016-2019 **Localization and navigation of autonomous air vehicles flying near the ground.**
Role: Principal Investigator until 10/2018
Funding: Research Foundation of the State of Minas Gerais (FAPEMIG/Brazil) – R\$60,000.00
- 2016-2019 **Robot Navigation in dynamic workspaces in the presence of uncertainties.**
Role: Principal Investigator until 10/2018
Funding: National Council for Scientific and Technological Development (CNPq/Brazil) – R\$39,600.00
- 2015-2016 **Navigation of autonomous aerial vehicles near the ground.**
Role: Principal Investigator
Funding: National Council for Scientific and Technological Development (CNPq/Brazil) – US\$29,984.00
- 2013-2016 **Motion Planning, Coordination and Control of Cooperating Robots.**
Role: Principal Investigator
Funding: National Council for Scientific and Technological Development (CNPq/Brazil) – R\$39,600.00
- 2013-2015 **Navigation of Cooperative Robots.**
Role: Principal Investigator
Funding: Research Foundation of the State of Minas Gerais (FAPEMIG/Brazil) – R\$48,000.00
- 2010-2015 **Mini-UAVs for Coverage of Areas with Minimization of Time.**
Role: Researcher
Funding: Financiadora de Estudos e Projetos (FINEP/Brazil) – R\$2,000,000.00
- 2012-2014 **Physical Human-Robot Interaction Using Position, Force, and Vision.**
Role: Principal Investigator
Funding: National Council for Scientific and Technological Development (CNPq/Brazil) – R\$22,000.00
- 2011-2014 **Towards Robust Robotic Manufacturing.** Research project between the Federal University of Minas Gerais, University of Brasília, and the Massachusetts Institute of Technology (MIT).
Role: Researcher
Funding: National Council for Scientific and Technological Development (CNPq/Brazil) – US\$57,000.00 – and MISTI Global Seed Funds – US\$30,000.00
- 2011-2013 **Navigation of Autonomous Vehicles in Outdoors Environments.**
Role: Principal Investigator
Funding: Research Foundation of the State of Minas Gerais (FAPEMIG/Brazil) – R\$48,000.00

2010-2012	Navigation of Cooperative Robots. Role: Principal Investigator Funding: National Council for Scientific and Technological Development (CNPq/Brazil) – R\$39,600.00
2009-2012	Boundary Coverage with Teams of Robots Using Vector Fields. Role: Researcher Funding: National Council for Scientific and Technological Development (CNPq/Brazil) – R\$30,000.00
2009-2011	Navigation of Autonomous Vehicles in Outdoors Environments. Role: Principal Investigator Funding: Research Foundation of the State of Minas Gerais (FAPEMIG/Brazil) – R\$48,000.00
2009-2011	Development of Techniques for Kinematic and Dynamic Analysis of Vehicles. Role: Principal Investigator Funding: Research Foundation of the State of Minas Gerais (FAPEMIG/Brazil) – R\$250,000.00
2007-2011	Coordination and Control of Large Groups of Robots. Research project between the Federal University of Minas Gerais and the University of Pennsylvania (UPENN). Role: Researcher Funding: National Council for Scientific and Technological Development (CNPq/Brazil) – US\$27,000.00 – and National Science Foundation (NSF/USA) – US\$5,000.00
2007-2010	Localization and Control of Cooperative Mobile Robots. Role: Principal Investigator Funding: National Council for Scientific and Technological Development (CNPq/Brazil) – R\$39,600.00
2007-2009	Hardware and Software for Localization, Navigation and Control of Autonomous Vehicles in Outdoor Environments. Role: Principal Investigator Funding: Research Foundation of the State of Minas Gerais (FAPEMIG/Brazil) – R\$48,000.00
2007-2009	Development of Instrumentation, Navigation and Control Systems for Aircrafts. Role: Researcher Funding: National Council for Scientific and Technological Development (CNPq/Brazil) – R\$300,000.00
2007-2009	Cooperation between Aerial and Ground Robots. Role: Researcher Funding: National Council for Scientific and Technological Development (CNPq/Brazil) – US\$25,000.00
2005-2006	Sensor Fusion for Localization of Autonomous Vehicles in Outdoor Environments. Role: Principal Investigator Funding: Research Foundation of the State of Minas Gerais (FAPEMIG/Brazil) – R\$48,000.00

Industrial Consulting and Research Partnership

- Petrobrás (2018) - Remote inspection of offshore platforms' construction.
- IHM Engineering (2017-2018) - Consulting on Drone navigation and mapping.
- VMI Security (2014) (2018) - Consulting on x-ray image formation, detection and processing of different materials on x-rays.
- Maxtrack Vehicle Trackers (2015) - Algorithms for tracker calibration and crash detection.
- FURNAS Centrais Elétricas (2012–2014) - Computer vision for reading meters' displays
- CEMIG (2000–2001) (2008) - A robot for installation of signaling spheres; Algorithms and data structures course.

Languages

PORTUGUESE	Native speaker.
ENGLISH	Advanced level.
SPANISH	Comprehends reasonably and reads well.

March 17, 2021